#### Voronoi Choice Games

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#### Political Candidate Selection

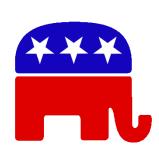










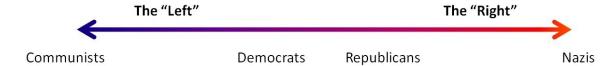


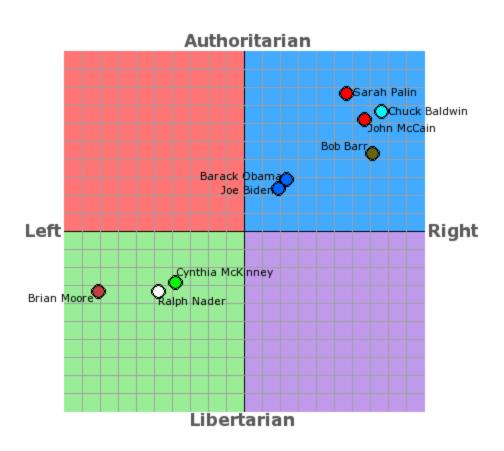






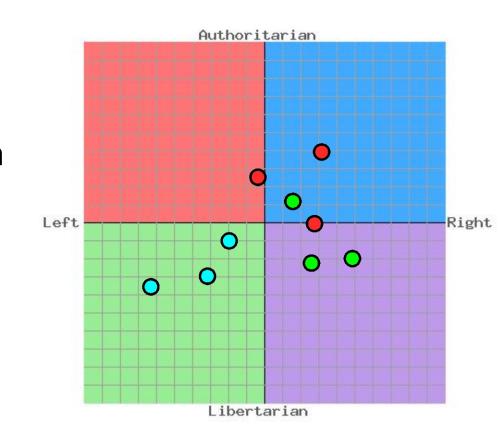
#### **Political Positions**





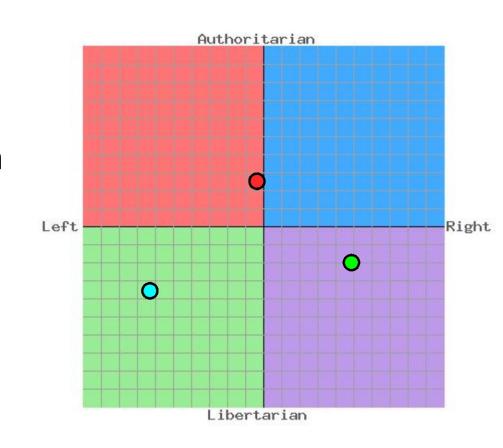
#### Candidates Selection Game

- Political candidate selection
  - n parties, each with a separate pool of candidates
  - Simultaneously pick candidates so as to maximize votes



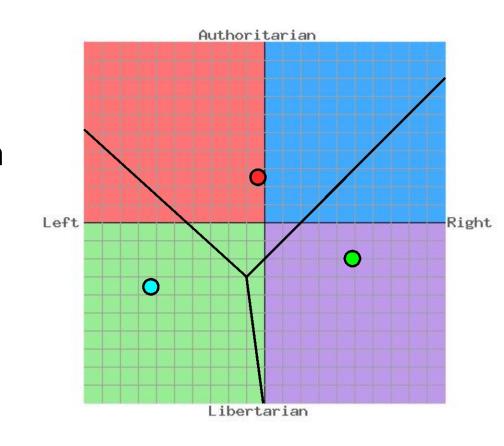
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#### Models

- k-D Voronoi Choice Game
  - k dimensional unit torus
  - n players
  - Each player has m (small constant) points
  - Each player simultaneously picks a point
  - Utility = area of point's cell in Voronoi diagram
- One Way 1-D Voronoi Choice Game
  - Utility = distance to next point clockwise

#### Related Games

- Voronoi Games
  - Two player
  - Unconstrained choices
  - Sequential games
- Hotelling Games
  - AKA competitive location games
  - Sometimes limited choices, but always symmetric
  - On line or graph
- Main difference with our model: player asymmetry

#### Summary of Results

- Proof of existence of pure Nash equilibria for the 1-D Voronoi Choice Game
- NP-hardness of pure Nash equilibria in One Way 1-D Voronoi Choice Game
- Strong bounds on the expected number of pure Nash equilibria in random versions of the One Way 1-D Voronoi Choice Game
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- Model: One Way 1-D (n players, m choices each)
- Each player's points are independently chosen uniformly at random
- Motivation: "power of choice" in load balancing
- The expected number of PNE in the One Way 1-D Voronoi Choice Game is in [.19<sup>m-1</sup> m, m]
  - Small constant (for small m), no dependence on n

A player's point **choice** is **stable** in a configuration if they won't deviate from it

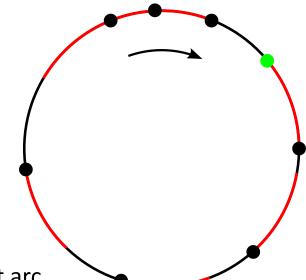
A circle arc is stable if the point that starts it is stable

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E[# PNE] = m<sup>n</sup> Pr[first choices are stable]
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- = m<sup>n</sup> E[Pr[first choices are stable | positions of first choices]]
- =  $m^n E[\prod_{i=1}^n Pr[ith player is stable | positions of first choices]]$
- =  $m^n E[\prod_{i=1}^n Pr[ith smallest arc is stable|positions of first choices]]$

Pr[ith smallest arc is stable | positions of first choices]?

Red are regions which green player would not deviate to

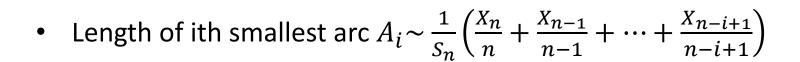


 $A_i$  = length of the ith smallest arc

Pr[ith smallest arc is stable | positions of first choices]

$$= \left( (n-i)A_i + \sum_{j=1}^i A_j - \min(A_i, \text{ length of arc before i}) \right)^{m-1}$$

- Now a question about the lengths of random arcs on circles
- Distance between points is exponentially distributed
- Take order statistics of those exponentials



- $X_i$  are i.i.d. exponential random vars with mean 1
- $S_j = X_1 + \cdots + X_j$

Pr[ith smallest arc is stable | positions of first choices]

$$= \left( (n-i)A_i + \sum_{j=1}^i A_j - \min(A_i, \text{ length of arc before i}) \right)^{m-1}$$

$$\in \left[ \left( \frac{S_i}{S_n} - A_i \right)^{m-1}, \left( \frac{S_i}{S_n} \right)^{m-1} \right]$$

- $E[\# PNE] \le m^n E\left[\prod_{i=1}^n \left(\frac{S_i}{S_n}\right)^{m-1}\right] = m$
- $S_n$ ,  $\left(\frac{S_1}{S_2}\right)$ ,  $\left(\frac{S_2}{S_3}\right)$ , ...,  $\left(\frac{S_{n-1}}{S_n}\right)$  are independent

• 
$$E[\# PNE] \ge m^n E\left[\prod_{i=1}^n \left(\frac{S_i}{S_n} - A_i\right)^{m-1}\right]$$
  
 $\ge m^n E\left[\prod_{i=1}^n \left(\frac{c_i S_i}{S_n}\right)^{m-1}\right] \ge .19^{m-1} m$ 

- A correlated equilibrium (CE) is a generalization of Nash equilibrium to allow player strategies to be correlated
- (Papadimitriou & Roughgarden, 2008) and (Jiang & Leyton-Brown, 2013) developed polytime algorithm for CE in games of polynomial-type
- Requires a polytime oracle for computing the expected utility given a product distribution over strategies (each player is independent)

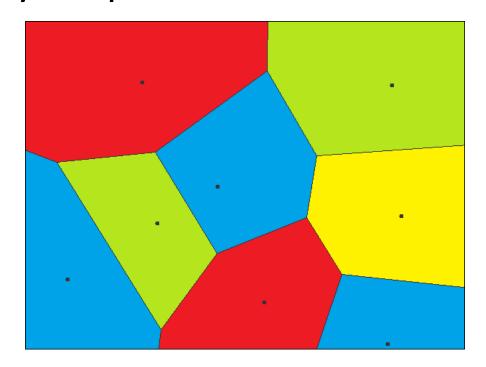
- **Goal:** compute the expected utility over a product distribution for 1-D Voronoi Choice Games
- For each player point, compute the expected distance from that point to the next chosen point in each direction
- Sort the points and iterate through them in order, computing the probability that each point is the first chosen point

$$d_1 \qquad d_2 \qquad d_3 \qquad p_3$$

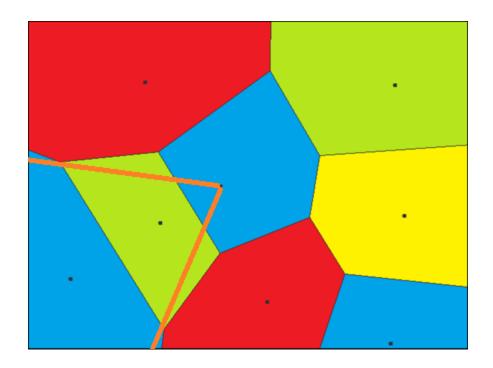
E[right dist] = 
$$p_1d_1+(1-p_1)p_2d_2+(1-p_1)(1-p_2)p_3d_3+...$$

Stop once we reach a player's last point

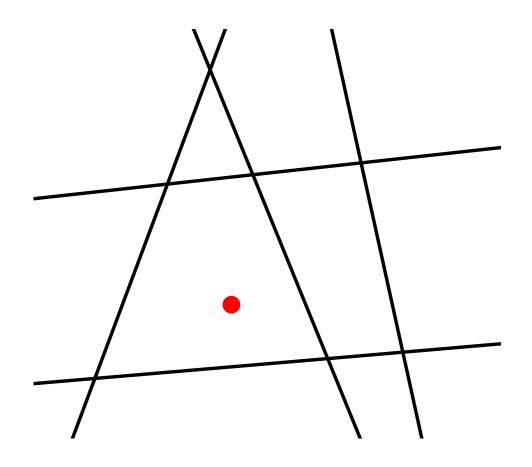
- What about 2D?
- A given Voronoi cell can be bounded by many other players' points



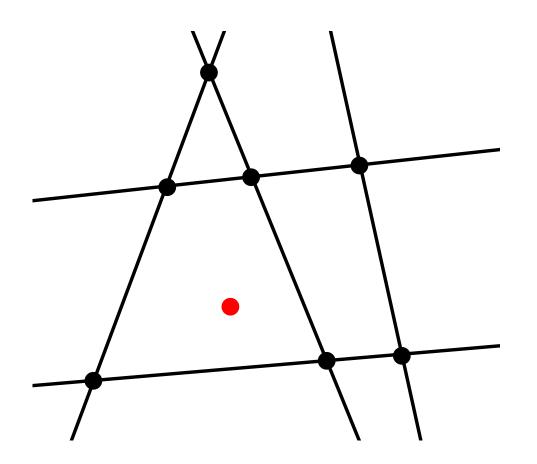
 Idea: partition space into regions where the 1D strategy works



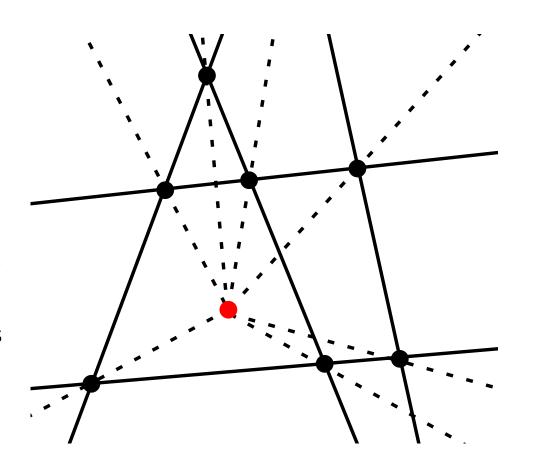
- Compute the expected utility of a given point:
  - Each other point yields a boundary line



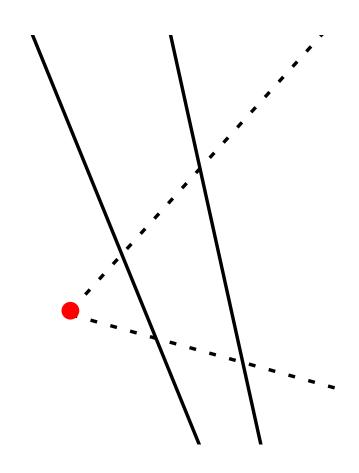
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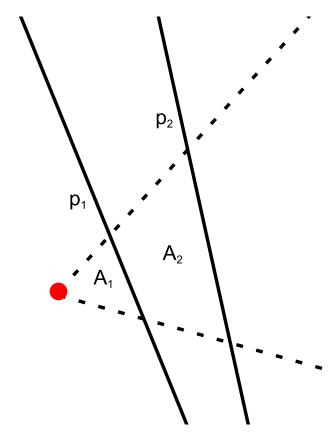
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  - Sort those points by angle
  - Decompose area into regions in between angles



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  - In each region iterate through boundary lines as in 1D



E[area in region] = 
$$p_1A_1 + (1-p_1)p_2A_2 + ...$$

- Time =  $O(n^3 \log n)$ 
  - O(n) boundary lines  $\rightarrow O(n^2)$  regions
  - O(n log n) time per region to sort lines and iterate
- Can reduce to O(n³) by not resorting each time
  - Only one swap between adjacent regions
- Same basic principles get us O(n<sup>5</sup> log n) in 3D

#### **Open Questions**

- Probability of any PNE in random model?
- Correlated equilibria in 4D+?
- What about mixed Nash equilibria?
- Sequential versions of these games?

#### **Thank You**