

Polynomial Time corresponds to Solutions of Polynomial Ordinary Differential Equations of Polynomial Length

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July 13, 2015

Main result and consequences

Theorem (Informal)

$\text{PTIME} = \text{PIVP}$ of polynomial length

PIVP: Ordinary Differential Equations (ODE) with polynomial right-hand side.

- ▶ **Implicit complexity:** purely continuous (time and space) characterization of PTIME
- ▶ **Continuous-time models of computations:** Turing machines and the GPAC are equivalent at the complexity level

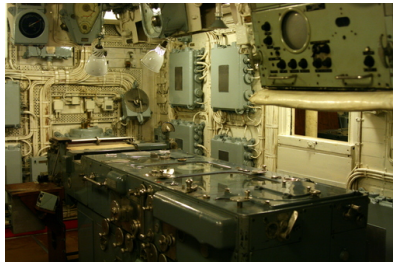
Digital vs analog computers



Digital vs analog computers



VS



Let's model!

Physical Computer	Model
Laptop, ...	Turing machines λ -calculus Recursive functions Circuits Discrete dynamical systems
Differential Analyzer, ...	GPAC Continuous dynamical systems

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Implicit corollary

Some models are **too general/unreasonable**.

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Differential Analyzer, ...	GPAC → reasonable ? Continuous dynamical systems

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General Purpose Analog Computer (GPAC)

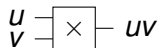
- ▶ invented by Shannon (1941)
- ▶ idealization of the Differential Analyzer:



- ▶ circuits made of:



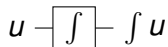
Constant



Multiplier



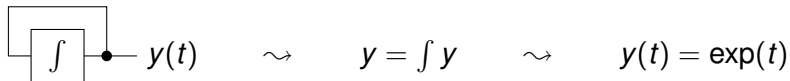
Adder



Integrator

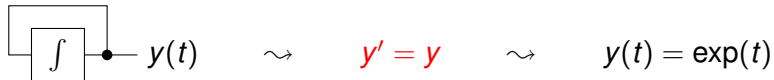
Examples of GPAC

Exponential:



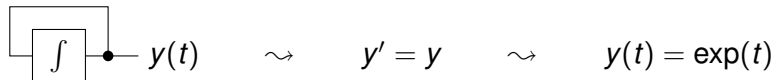
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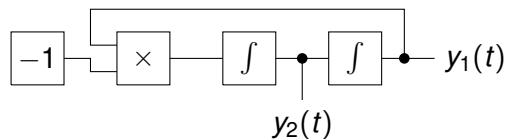


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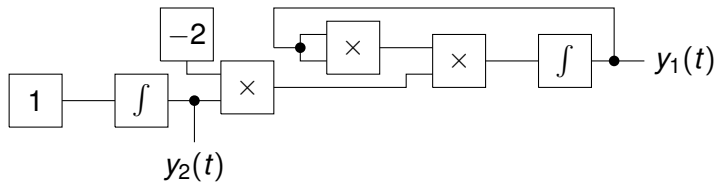
(Co)sine:



$$\begin{cases} y_1' = y_2 \\ y_2' = -y_1 \end{cases} \rightsquigarrow \begin{cases} y_1(t) = \sin(t) \\ y_2(t) = \cos(t) \end{cases}$$

Examples of GPAC

Rational function:



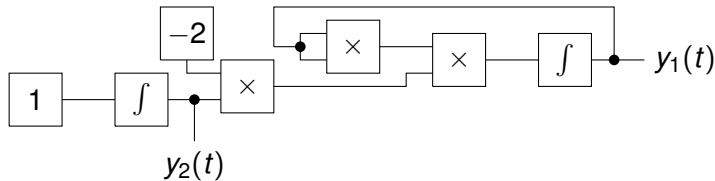
$$\begin{cases} y_1' = -2y_2y_1^2 \\ y_2' = 1 \end{cases}$$

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$$\begin{cases} y_1(t) = \frac{1}{1+t^2} \\ y_2(t) = t \end{cases}$$

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Theorem (Graça and Costa)

$y = (y_1, \dots, y_d)$ is generated by a GPAC iff it satisfies a Polynomial Initial Value Problem (PIVP):

$$\begin{cases} y' = p(y) \\ y(t_0) = y_0 \end{cases}$$

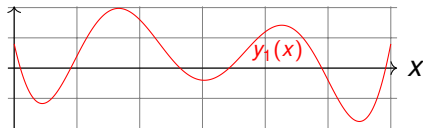
where p is a vector of polynomials.

Computing with the GPAC

Generable functions

$$\begin{cases} y(0) = y_0 \\ y'(x) = p(y(x)) \end{cases} \quad x \in \mathbb{R}$$

$$f(x) = y_1(x)$$



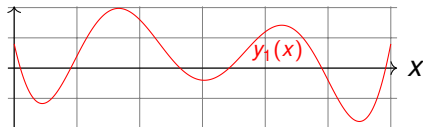
Shannon's notion

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sin, cos, exp, log, ...

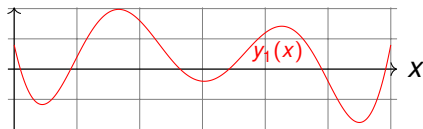
Strictly weaker than Turing machines [Shannon, 1941]

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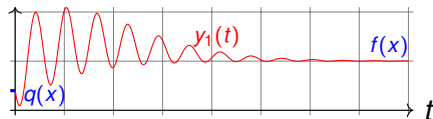
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$$\begin{cases} y(0) = q(x) \\ y'(t) = p(y(t)) \end{cases} \quad \begin{array}{l} x \in \mathbb{R} \\ t \in \mathbb{R}_+ \end{array}$$

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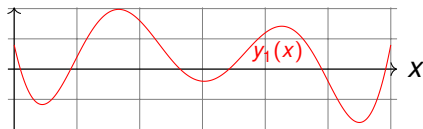
Modern notion

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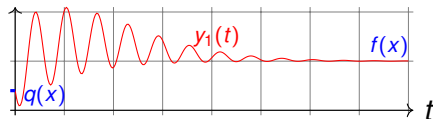
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Modern notion

sin, cos, exp, log, Γ , ζ , ...

Turing powerful
[Bournez et al., 2007]

Different kinds of equivalence

Theorem (Bournez et al)

The GPAC is equivalent to Turing machines for **computability**.

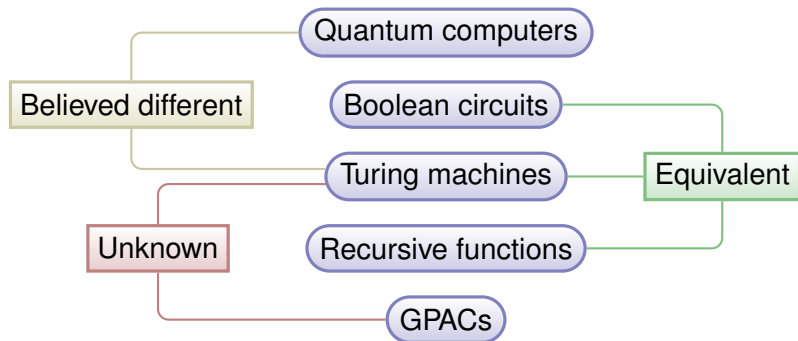
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- ▶ Computability: compute the same functions
- ▶ Complexity: same functions with same “complexity”

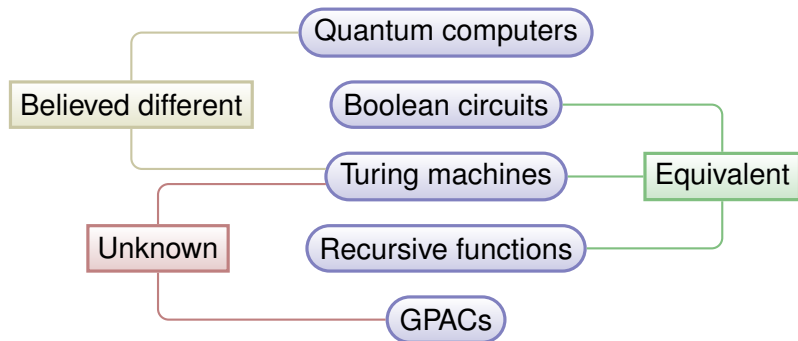


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Main Result of the paper

Turing machines and GPACs are equivalent for **complexity**.

Time complexity for continuous systems

- ▶ **Turing machines:** $T(x)$ = number of steps to compute on x

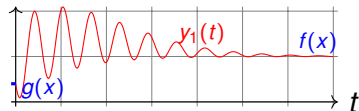
Time complexity for continuous systems

- ▶ **Turing machines:** $T(x)$ = number of steps to compute on x
- ▶ **GPAC:** time contraction problem

Intuitive definition

$T(x, \mu) =$ first time t so that $|y_1(t) - f(x)| \leq e^{-\mu}$

$$y(0) = q(x) \quad y' = p(y)$$



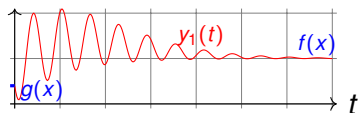
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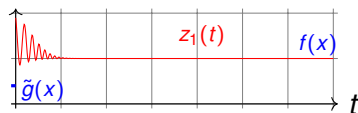
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\rightsquigarrow

$$z(t) = y(e^t)$$



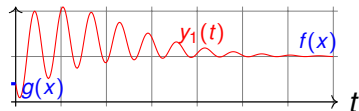
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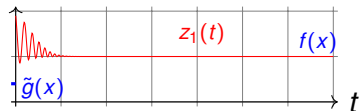
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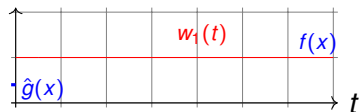
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$$w(t) = y(e^{e^t})$$



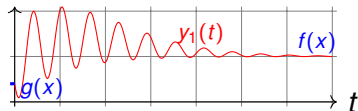
Time complexity for continuous systems

- ▶ **Turing machines:** $T(x)$ = number of steps to compute on x
- ▶ **GPAC:** time contraction problem \rightarrow **open problem**

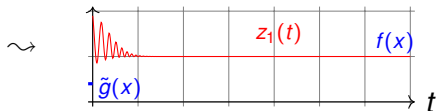
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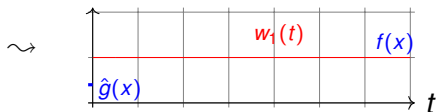
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Observation

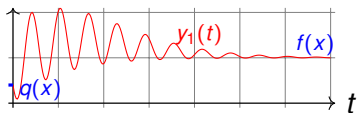
This definition is broken:
all functions have arbitrarily small complexity.

$$w(t) = y(e^{e^t})$$



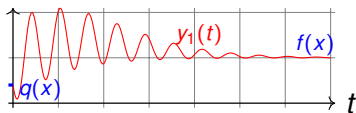
Time-space correlation of the GPAC

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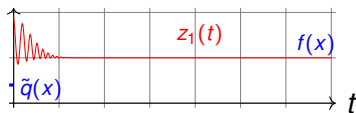
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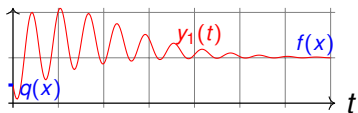
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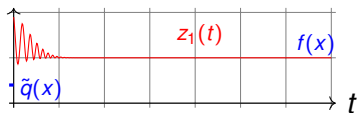
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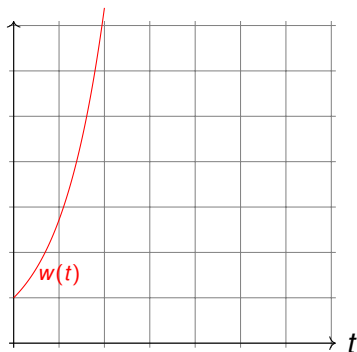


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extra component: $w(t) = e^t$

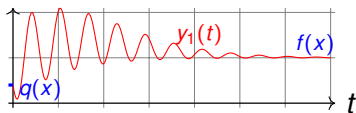


Observation

Time scaling costs “space”.

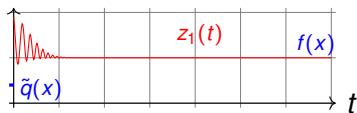
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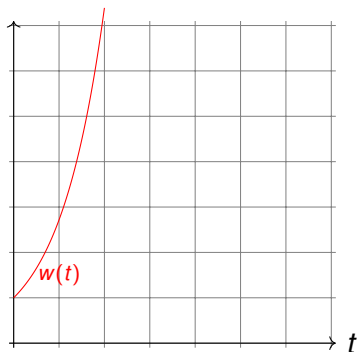
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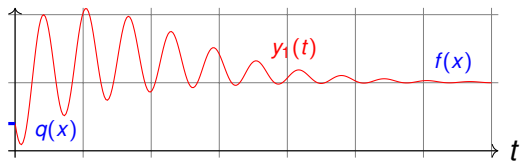
\rightsquigarrow

Time complexity for the GPAC must involve time and **space** !

extra component: $w(t) = e^t$



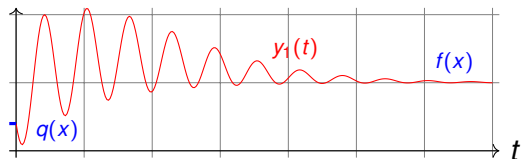
Two equivalent notions of complexity



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Length based complexity: L

$\ell(t)$ = length of y over $[0, t]$

$$= \int_0^t \|p(y(u))\| du$$

$L(x, \mu)$ = length $\ell(t)$ so that

$$\|y_1(t) - f(x)\| \leq e^{-\mu}$$

Characterization of Turing polynomial time

Definition: $\mathcal{L} \subseteq \{0, 1\}^*$ is **polytime-recognizable** iff for all w :

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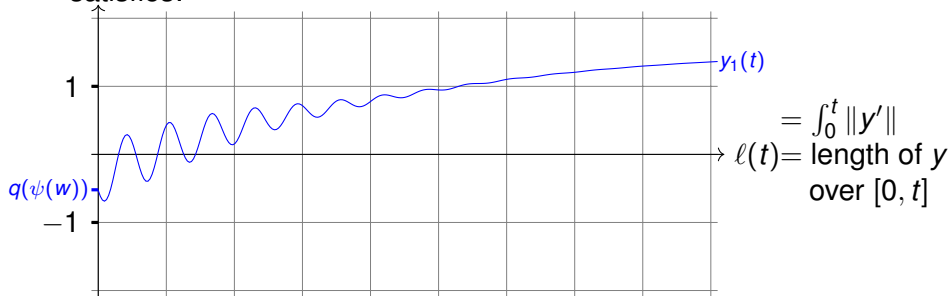
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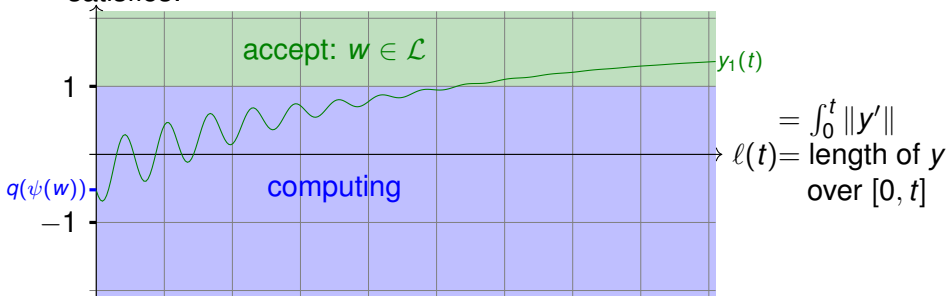


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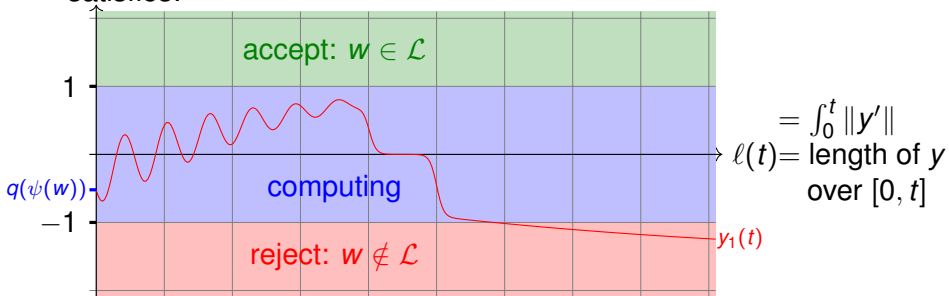
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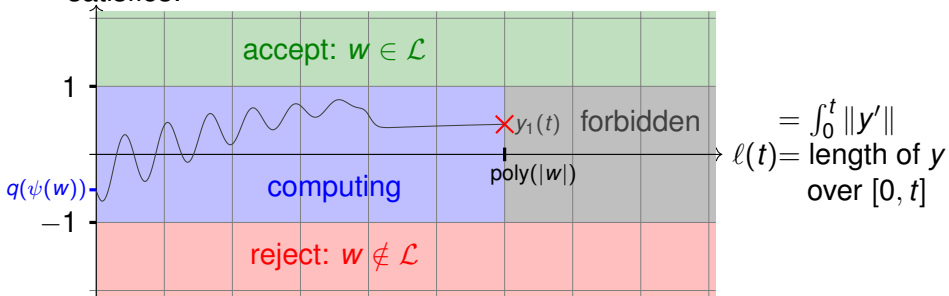
② if $y_1(t) \leq -1$ then $w \notin \mathcal{L}$

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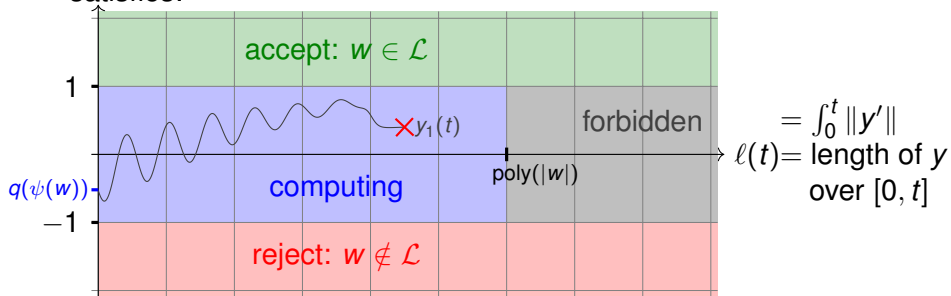
③ if $\ell(t) \geq \text{poly}(|w|)$ then $|y_1(t)| \geq 1$

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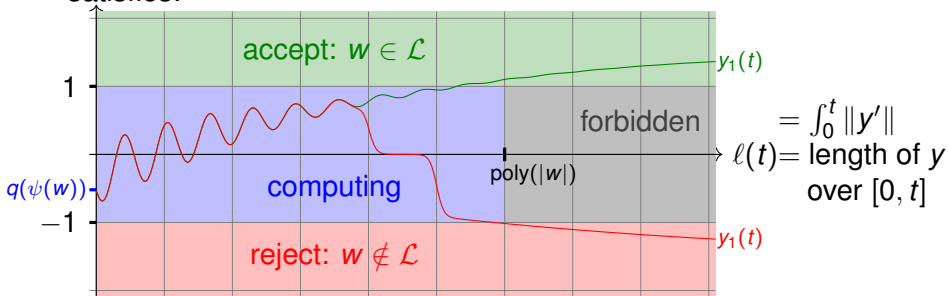
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Theorem

$\mathcal{L} \in \text{P}$ if and only if \mathcal{L} is polytime-recognizable.

Characterization of real polynomial time

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$$\text{where } \ell(t) = \int_0^t \|y'(u)\| du$$

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Main result

$f : [a, b] \rightarrow \mathbb{R}$ is polytime computable iff f is analog-polytime.

Conclusion

- ▶ Time complexity for the GPAC: length or time+space
- ▶ Turing machines and GPACs are equivalent for time complexity
- ▶ Purely analog and machine-independent characterization of (discrete and real) polynomial time

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Perspectives:

- ▶ Better understanding of time complexity
- ▶ Space complexity
- ▶ Nondeterminism
- ▶ Constants (a.k.a getting rid of π)
- ▶ Robustness of errors/perturbations



Bournez, O., Campagnolo, M. L., Graça, D. S., and Hainry, E. (2007).

Polynomial differential equations compute all real computable functions on computable compact intervals.
23(3):317–335.



Shannon, C. E. (1941).

Mathematical theory of the differential analyser.
Journal of Mathematics and Physics MIT, 20:337–354.