

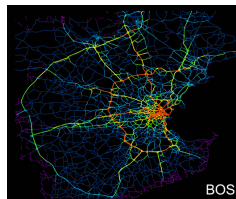
# On the Size and the Approximability of Minimum Temporally Connected Subgraphs

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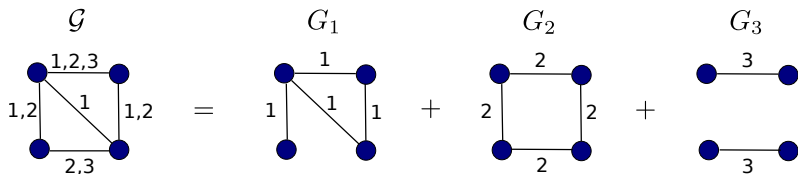
# Motivation

- ▶ Graphs are a very useful abstract model...
- ▶ ...but traditional connectivity is a static measure
- ▶ In real-world applications connectivity "changes" through time
  - ▶ Transportation networks: Roads temporarily closed for maintenance
  - ▶ Social networks: Social interactions are not invariant
  - ▶ More generally, distributed computation and information spreading



# Temporal graphs

- ▶ We need to generalize our model to graphs that capture changes in time...
- ▶ ...**Temporal** graphs!
- ▶ A sequence of usual undirected weighted graphs with invariant vertex set:  $(G_t(V, E_t, w_t))_{t \in [L]}$  ( $L$  is called *lifetime*)

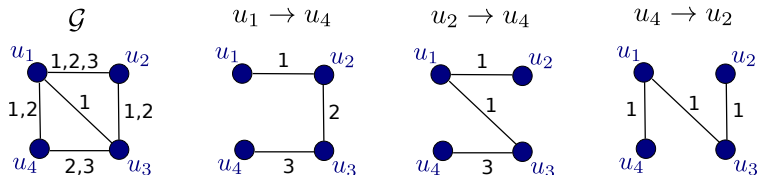


# Temporal graphs (cont.)

- ▶ The *underlying* (usual) graph is  $G(V, E)$  with  $E = \bigcup_{t \in L} E_t$
- ▶ *Simple* temporal graph: Each edge available for at most one time moment
- ▶ Denote  $N = |V|$ ,  $M = \sum_{t \in [L]} |E_t|$

# Temporal path

- ▶ *Temporal path* from  $u_1 \in V$  to  $u_k \in V$ : A path from  $u_1$  to  $u_k$  in  $G$ , but edges also equipped with non-decreasing time labels along the path



- ▶ Formally:  $u_1, (e_1, t_1), u_2, (e_2, t_2), \dots, u_k$ , where  $t_i \leq t_{i+1}$  and  $\{u_i, u_{i+1}\} \equiv e_i \in E_{t_i}$
- ▶ Intuitively: Starting at  $u_1$  at time 0, we eventually reach  $u_k$

- ▶ To study connectivity, we need temporal analogues of connectivity and minimum connectivity certificates (minimum spanning trees)
- ▶ **Temporal connectivity**: There is a temporal path between each (ordered) pair of vertices
- ▶ **Minimum Temporally Connected Subgraph** (Spanning tree analogue): A temporal graph  $\mathcal{G}'(V, E', w)$  with  $E'_t \subseteq E_t, \forall t \in [L]$  such that  $\mathcal{G}'$  is temporally connected, where  $\sum_{t \in L} w_t(E'_t)$  is minimum
- ▶ Intuitively: We "buy" each edge for a subset of time instants, and still preserve temporal connectivity

- ▶ [Berman, '96] presented an algorithm for reachability by temporal paths and proved a temporal analogue of the max-flow min-cut theorem
- ▶ [Kempe, Kleinberg, Kumar, '00] investigated the temporal generalization of certain graph properties (e.g Menger's theorem not true), showed worst-case MTCS size is  $\Omega(N \log N)$  and  $O(N^2)$
- ▶ [Mertziotis, Michail, Chatzigiannakis, Spirakis, '13] proved that a variant of Menger's theorem holds

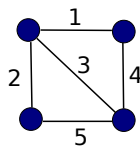
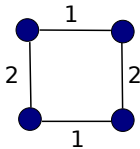
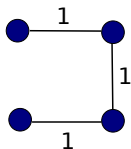
## Previous work (cont.)

- ▶ [Erlebach, Hoffmann, Kammer, '15] showed that shortest *exploration schedules* can require  $\Theta(N^2)$  steps
- ▶ [Akrida, Gasieniec, Mertzios, Spirakis, '15] showed a  $\Theta(N \log N)$  lower bound on MTCS size by *strict* temporal paths, on graphs with distinct time labels. Also showed that computing the max number of edges to remove to preserve connectivity is APX-hard



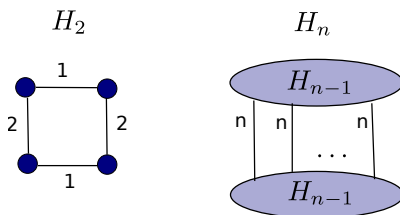
# Minimum Temporally Connected Subgraph size

- ▶ In usual graphs, all minimum connectivity certificates have size  $n - 1$
- ▶ In temporal graphs, this is not the case!



# Minimum Temporally Connected Subgraph size (cont.)

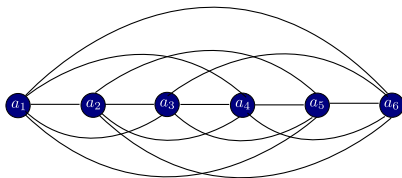
- ▶ Natural question (posed by Kempe et al (STOC 2000)):  
What is the worst-case size of a minimum temporally connected subgraph? (For *simple* temporal graphs)
- ▶ At least  $\Omega(N \log N)$ :



- ▶ We bridge the  $\Omega(N \log N)$ - $O(N^2)$  gap by showing that it is  $\Theta(N^2)$

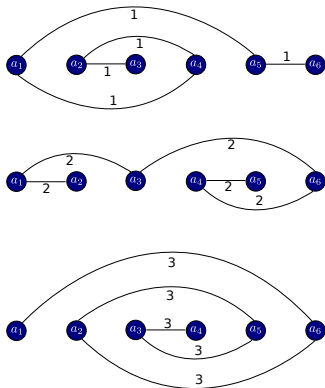
# Lower bound on MTCS size

- ▶ We need a **dense**, simple, temporally connected graph, where the deletion of any edge breaks temporal connectivity
- ▶ First part: A linear number of "independent" paths, each of linear size, that share the same vertex set of size  $N$ .
- ▶ Partition a complete graph into  $\frac{N}{2}$  Hamiltonian paths



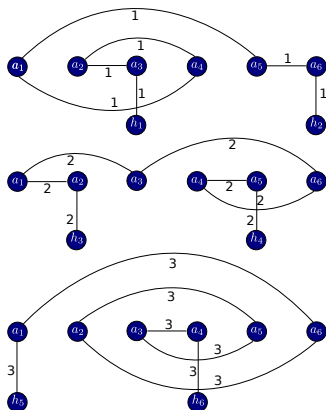
# Lower bound on MTCS size (cont.)

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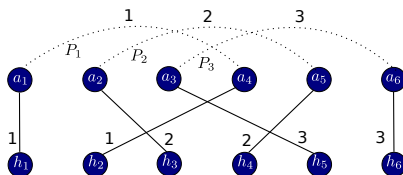
## Lower bound on MTCS size (cont.)

- ▶ Connect  $N$  extra vertices, each to the endpoint of one path, with the same label as the path
- ▶ All  $N + 1$  edges of the  $i$ -th Hamilton path have time label  $i$



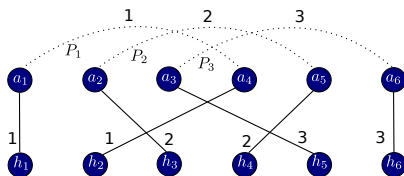
# Lower bound on MTCS size (cont.)

- ▶ First (density) part: A linear number of "independent" paths, each of linear size, that share the same vertex set of size  $N$ .



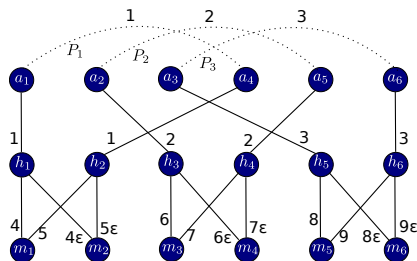
## Lower bound on MTCS size (cont.)

- ▶ Second (interconnection) part: Connect the  $h_i$ 's to each other
- ▶ Add  $N$  extra nodes, but careful not to introduce alternative temporal paths between  $h_{2i}$  and  $h_{2i-1}$  (technical)
- ▶ Each pair of these extra nodes correspond to a specific Hamilton path, are seen as an "entry" and an "exit" node respectively (to/from the path's endpoints)



# Lower bound on MTCS size (cont.)

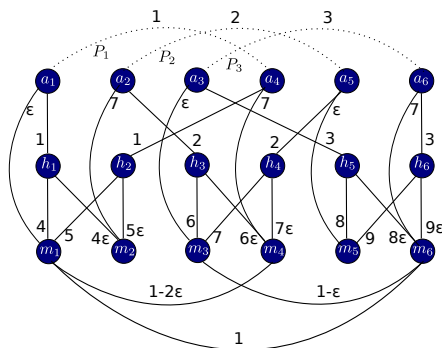
- ▶ Second (interconnection) part: Connect the  $h_i$ 's to each other
- ▶ Add  $N$  extra nodes, but careful not to introduce temporal paths between internal vertices of Hamilton paths (technical)
- ▶ Each pair of these extra nodes correspond to a specific Hamilton path, are seen as an "entry" and an "exit" node respectively (to/from the path's endpoints)





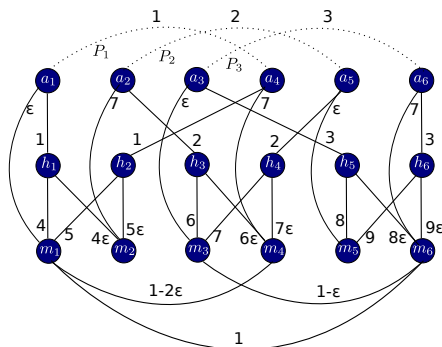
# Lower bound on MTCS size (cont.)

- ▶ Second (interconnection) part: Connect the  $h_i$ 's to each other



# Lower bound on MTCS size (cont.)

- ▶ Remove any edge with label  $i$  from the first part  $\Rightarrow$  impossible to move from  $h_{2i}$  to  $h_{2i-1}$
- ▶ Construction forces each temporal path to start and end at time  $i$
- ▶ Therefore all  $\Theta(N^2)$  edges of the first part are essential



## Lower bound on MTCS size (cont.)

- ▶ Summary: A simple, minimal, temporally connected graph with  $\Theta(N)$  vertices and  $\Theta(N^2)$  edges
- ▶ Note: We can make the size of the *MTCS* linear, by changing just one label in the above construction!

- ▶ **Minimum Temporally Connected Subgraph** (Spanning tree analogue): A temporal graph  $\mathcal{G}'(V, E', w)$  with  $E'_t \subseteq E_t, \forall t \in [L]$  such that  $\mathcal{G}'$  is temporally connected, where  $\sum_{t \in L} w_t(E'_t)$  is minimum

- ▶ What's next? Study the problem of computing Minimum Temporally Connected Subgraphs
- ▶ 2 useful variations:
  - ▶  $r - MTC$ : Compute a minimum weight temporal subgraph, so that there are temporal paths from a fixed  $r \in V$  to all  $u \in V$
  - ▶  $MTC$ : Compute a minimum weight temporally connected subgraph
- ▶ Both problems are very hard

- ▶ Central idea of all reductions: Time dependence induces implicit direction
- ▶ Temporal connectivity problems are closely related to directed *Steiner* problems

$r$  – MTC:

- ▶ Optimal solution is a tree
- ▶ Essentially equivalent to Directed Steiner Tree
- ▶ No  $O(\log^{2-\epsilon} N)$  approximation unless  $NP \subseteq ZTIME(n^{\text{poly} \log n})$  (reduction from DST)
- ▶  $O(N^\epsilon)$  approximation  $\forall \epsilon$  (reduction to DST)
- ▶ Easy to solve in polynomial time for unweighted graphs (Prim-like algorithm)

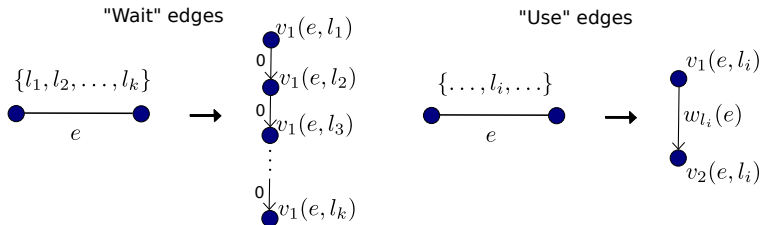
## MTC:

- ▶ No  $O(2^{\log^{1-\epsilon} N})$  approximation unless  $NP \subseteq DTIME(n^{\text{poly} \log n})$  (reduction from Label Cover)
- ▶ Trivial  $O(N^{1+\epsilon})$  approximation: Run  $r - MTC$  algorithm for each node as source
- ▶ APX-hard even for unweighted graphs (reduction from  $\{1, 2\}$ -Steiner tree), but trivial  $L$ -approximation (pick any spanning tree at each instant)



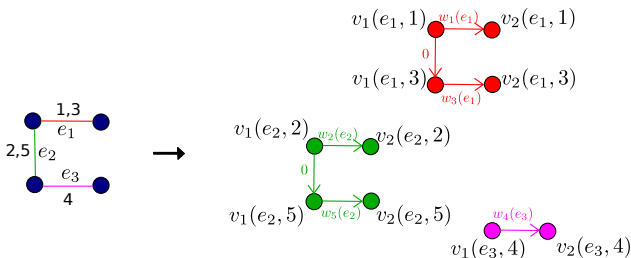
# MTC $\rightarrow$ DSF reduction

- ▶ All MTC hardness results hold even for constant lifetime
- ▶ Better approximation for MTC for sparse temporal graphs with a reduction to Directed Steiner Forest
- ▶ Create two nodes for each temporal edge (edge-label pair)
- ▶ Add "wait" edges and "use" edges



# MTC $\rightarrow$ DSF reduction (cont.)

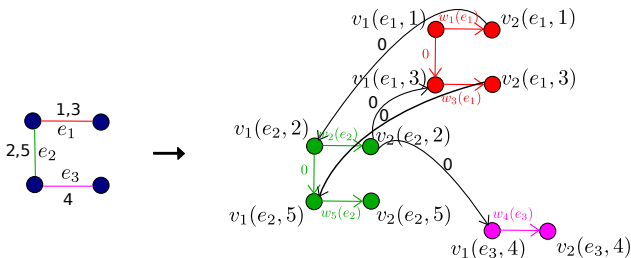
Example



- ▶ Add "move" edges (move from one edge to another)
- ▶ For near-linear number of temporal edges and polylogarithmic max degree, we get an  $O(N^{2/3+\epsilon})$  approximation
- ▶ An  $O(N^{1/6})$  approximation for the general MTC would improve the best-known  $\tilde{O}(N^{1/3})$  approximation for MIN-REP Label Cover

# MTC $\rightarrow$ DSF reduction (cont.)

Example



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## $r - MTC$ , $MTC$ in restricted graph families

- ▶ We can do much better if we restrict the underlying graph family
- ▶  $r - MTC$  in polynomial time for bounded treewidth underlying graphs
- ▶  $MTC$  in polynomial time for temporal trees
- ▶  $MTC$  2-approximable for temporal cycles

- ▶ General *MTC* is too hard, can we get a better constant than  $L$  for the approximability in the unweighted case?
- ▶ Or maybe some algorithm to recognize instances with quadratic size connectivity certificate
- ▶ Other special cases with good approximation ratio (Moreover, is the 2-approximation for the temporal cycle tight?)

# Thank you!

Questions?